

Name:
Enrolment No:



UNIVERSITY OF PETROLEUM AND ENERGY STUDIES
End Semester Examination, January 2021

Course: Embedded Systems
Program: M. Tech A&RE
Course Code: ECEG7003

Semester: I
Time 03 hrs.
Max. Marks: 100

Instructions: Read all the questions carefully. Assume any missing data.

SECTION A

S.No.	Answer All the questions	Marks	CO
1	In brief, explain the advantages and disadvantages of hardware/software co-design process in embedded systems	5	CO3
2	In ATmega8, list the different types of memories available along with the size and use of each	5	CO1
3	In ARM, define pipelining and explain the difference between 3-stage and 5-stage pipelining	5	CO4
4	In LPC2148, highlight the differences between the thumb and Jazelle mode of operation in detail	5	CO1
5	Elucidate the differences between pull-up and pull-down resistors for the operation of microcontrollers.	5	CO4
6	What is the role of CGRAM, DDRAM memories of LCD?? Out of the two which register is programmable by the user??	5	CO2

SECTION B

S.No	Answer all the questions	Marks	CO
7	In ARM with an example for each for both hexadecimal and binary data, explain the working of i) PINSEL Register ii) IODIR Register iii) IOSET Register iv) IOCLR register	10	CO1
8	Considering the electronic equipment's required for a smart home, classify them into different types of embedded systems. With respect to manufacturing, power and energy cost, enlist the devices in ascending order.	10	CO2
9	Interface and LCD to LPC2148 to display your name in first row and your SAP ID in second row. Write the complete algorithm and code. Draw the necessary flowchart required	10	CO3
10	In AVR what are the different system clock options available to provide the clock source? Draw the complete block diagram and mention the function of each block	10	CO4

11	Into how many modes and LPC2148 can be operated? Explain the function of each mode along with the registers required for each mode.	10	CO2
SECTION-C			
S.No	Answer all the questions	Marks	CO
12	Consider an LCD, 8 LEDs, DC motor to be interfaced with AVR/Arduino. The motor should be rotated in clockwise and anti-clockwise direction. The direction of rotation has to be displayed on LCD and LEDs. Write the complete algorithm and code required along with the schematic/block diagram and flowchart	20	CO3