Name:

Enrolment No:



UPES End Semester Examination, May 2023

Course: Theory of Machines Program: B.Tech – Mechatronics Course Code: MECH 2013 Semester: IV Time: 03 hrs. Max. Marks: 100

Instructions: Assume suitable data. Attempt graphical questions on A3 sheets provided. Q 9 and Q 11 have internal choices.

S. No.	(5Qx4M=20Marks)		CO		
		Marks	CO		
Q 1	1 Explain the term undercutting as applicable to gears.				
Q 2	Differentiate between Whitworth quick return mechanism and Crank and Slotted lever mechanism.	4 CO1			
Q 3	Explain in brief the application of cam and follower arrangement in any three machines.	4	CO1		
Q 4	Discuss different follower according to shape.	4	CO1		
Q 5	Explain Coriolis acceleration component with examples of mechanisms where it is applicable.	4	CO1		
	SECTION B				
	(4Qx10M= 40 Marks)				
Q 6	The addendum on each wheel of two mating gears is to be such that the line of contact on each side of the pitch point is half the maximum possible length. The number of teeth on the two gears is 24 and 48. The teeth are of 20 ^o pressure angle involute with a module of 12 mm. Determine the addendum for the pinion and the gear. Also, determine the arc of contact and contact ratio.	10	CO3		
Q 7	Each wheel of a four-wheeled rear engine automobile has a moment of inertia of 2.2 kg.m ² and an effective diameter of 600 mm. The rotating parts of the engine have a moment of inertia of 1.25 kg.m^2 . The gear ratio of the engine to the back wheel is 3.2. The engine axis is parallel to the rear axle and the crankshaft rotates in the same sense as the road wheels. The mass of the vehicle is 2050 kg and the centre of the mass is 520 mm above the road level. The track width of the vehicle is 1.6 m. Determine the limiting speed of the vehicle around a curve with 120 m radius so that all the four wheels maintain contact with the road surface.	10	CO3		
Q 8	In a compound epicyclic gear train as shown in the figure, gear A and an annular gears D & E are free to rotate on the axis P, B and C is a compound gear rotate about axis Q. Gear A rotates at 90 rpm CCW and gear D rotates at 450 rpm CW. Determine the speed and direction of rotation of arm F and gear E. Gears A, B	10	CO4		

	and C are having 18, 45 and 21 teeth respectively. All gears have same module				
	and pitch.				
	D E A B Q C Arm F				
0.0					
Q 9	9 For the slider-crank mechanism shown in figure below, determine the velocity of the point C on the link AB when the crank OA rotates at 180 rpm counterclockwise. OA = 500 mm, AB = 1500 mm and AC = 250 mm.				
	<u>OR</u>				
	Design a four-link mechanism to coordinate three positions of the input and the				
	output links for the following angular displacements.				
	$\begin{array}{ll} \theta_{12} = 60^{\circ} & \phi_{12} = 30^{\circ} \\ \theta_{13} = 90^{\circ} & \phi_{13} = 50^{\circ} \end{array}$				
	$\theta_{13} = 90^{\circ} \qquad \varphi_{13} = 50^{\circ}$				
	SECTION-C				
	(2Qx20M=40 Marks)				
Q 10	Use the following data and draw the profile of a cam in which a radial knife edge				
-	follower is raised with uniform acceleration and deceleration and is lowered with				
	simple harmonic motion:				
	Least radius of $cam = 60 \text{ mm}$				
	Lift of follower = 45 mm	20	CO4		
	Angle of ascent = 60°	20			
	Angle of dwell between ascent and descent = 40°				
	Angle of descent = 75°				
	If the cam rotates at 180 rpm, determine the maximum velocity and acceleration				
0.11	during ascent and descent.				
Q 11	A rotor has the following properties:	20	CO3		
1	Mass Magnitude Radius Angle Axial Distance from 1 st mass				
	$\frac{1}{1} \frac{9 \text{ kg}}{9 \text{ kg}} \frac{100 \text{ mm}}{100 \text{ mm}} \frac{0^{\circ}}{9 \text{ kg}}$				

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2	7 kg	120 mm	60°	160 mm				
3	8 kg	140 mm	135°	320 mm				
4	6 kg	120 mm	270°	560 mm				
If the s	haft is balan	ced by two	counter-m	asses located at 100 mm radii	and			
revolvin	ng in planes n	nidway of pl	anes 1 and	2, and midway of 3 and 4, deter	mine			
the mag	gnitude of the	masses and	l their respe	ctive angular positions. Justify	your			
answer	by graphical	method.						
<u>OR</u>								
Differentiate between static and dynamic balancing of rotating masses.							CO3	
Four m	accec A R ([¬] and D are	completel	y balanced. Masses C and D r	nake			
			-	•				
-		-	-	t of mass B in the counterclock	wise			
direction. The rotating masses have the following properties-								
		$m_{b} = 15$	5 kg r _a	= 360 mm				
		$m_{c} = 25$	ökg r _b	=480 mm				
		$m_{d} = 20$) kg r _c	= 240 mm				
			rd	= 300 mm				
Planes 1	Planes B and C are 250 mm apart. Determine the mass A and its angular position with that of mass B. Also find the positions of all the planes relative to plane of							
with the								
mass A								