Name:

**Enrolment No:** 



## UNIVERSITY OF PETROLEUM AND ENERGY STUDIES End Semester Examination, May 2023

Course: Autonomous Vehicle System Program: M.Tech Advanced Vehicle

**Course Code: MEAV 7009** 

Total no of pages:2

Semester: II

Time : 03 hrs.

Max. Marks: 100

## SECTION A (5Qx4M=20Marks)

S. No.		Marks	CO
Q 1	List the locomotion mechanism used in autonomous vehicle systems.	4	CO1
Q 2	State the key issues for locomotion in the autonomous vehicle navigation problem.	4	CO1
Q 3	List the possible wheel configuration for rolling mobile vehicle locomotion.	4	CO2
Q 4	State the significance of wheel geometry & maneuverability in autonomous moving vehicle.	4	CO2
Q 5	Discuss the concept of synchro drive for the indoor mobile vehicle applications.	4	CO2
	SECTION B		
	(4Qx10M=40 Marks)		
Q 6	Explain the control scheme for the autonomous moving vehicle for the palletising operation.	10	CO3
Q 7	Illustrate the concept of omnidirectional locomotion with four castor wheels and eight motors for autonomous off -road moving vehicle.	10	CO3
Q 8	Discuss the different types of sensors for mobile vehicle.	10	CO3

Q9	Explain the characterising error in the autonomous vehicle navigation in indoor application.  OR  Explain the concept of pinhole camera model while detecting the obstacle in indoor environment.	10	CO4
	SECTION-C (2Qx20M=40 Marks)		
Q 10	Describe the wheel kinematic constraints of the steered standard wheel of the outdoor applications.	20	CO4
Q 11	Suppose a differential drive vehicle has wheels of different diameters. The left wheel has diameter 2 inch and the right wheel has diameter 3 inch, $l=5$ inch for both wheels. The vehicle is positioned at $\theta=$ pi/4. The vehicle spins both wheels at a speed of 6 rpm. Compute the vehicle's instantaneous velocity in the global reference frame.		
	OR Determine the degree of mobility ,steer ability , and maneuverability for each of the following :  (a) bicycle (b)automobile	20	CO4