Name:

**Enrolment No:** 



# UNIVERSITY OF PETROLEUM AND ENERGY STUDIES

# End Semester Examination, December 2022

Programme Name: B.Tech Aerospace Engg

Course Name : Applied Fluid Mechanics Course Code : MECH2002 Semester : III Time : 03 hrs Max. Marks : 100

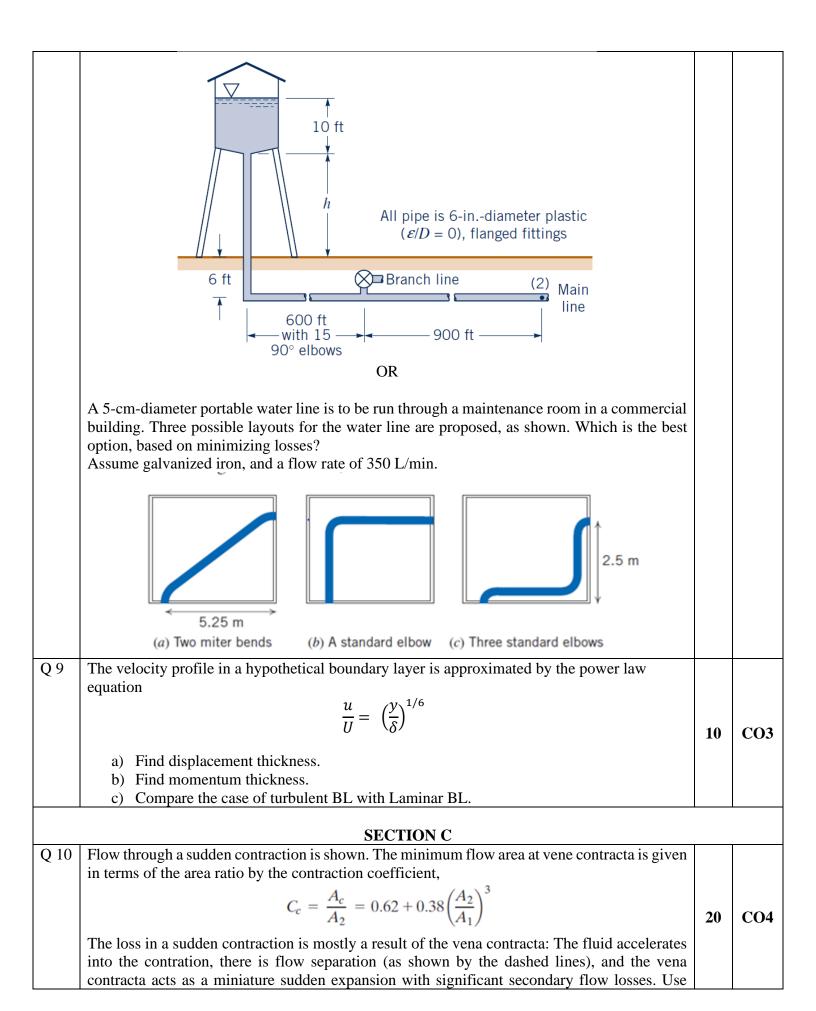
#### **Course Code Instructions:**

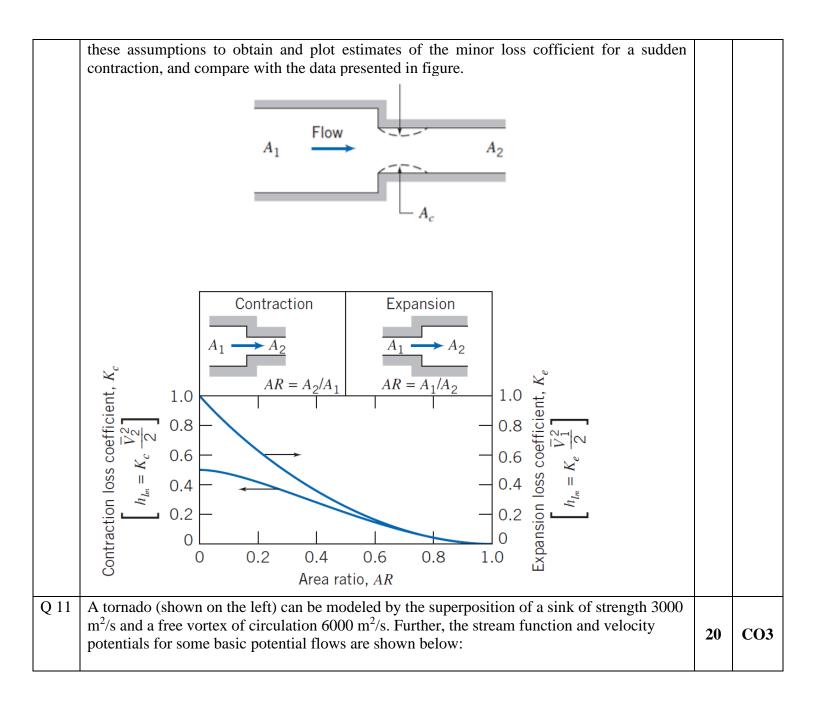
- Section A constitutes of 20 Marks (5 questions x 4 marks); Attempt All.
- Section B constitutes of 40 Marks (4 questions x 10 marks). Attempt All (One choice question).
- Section C constitutes of 40 Marks (2 questions x 20 marks). Attempt All (One choice question).

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SN			СО
Q1	The figure above shows that a table-tennis ball can be levitated in air by applying an air jet at an angle. Using a force-balance analysis, show how is this possible? Briefly state the possible physical effects and mathematical expressions underlying the phenomenon.	4	CO1
Q 2	A European Fluid Dynamicist, D' Alambert, once observed to his great surprise that $\underline{u, p_0}$ $\underline{u, p_0}$ $\mu = 0, \text{ Drag Force } F_D = 0$ 2) For $\mu \sim 0$ , Significant drag force $F_D$ 3) As $\mu$ is increased, $F_D$ is independent of $\mu$ .	4	CO1
Q 3	How do you explain such strange observations? Read these statements and answer the question that follow Mohan: Forced vortex is rotational. Murari: Free Vortex is irrotational. MadanMohan: Free Vortex is rotational. Madhusudan: Forced Vortex is irrotational.	4	CO1

# SECTION A

	Madhava: Forced and Free Vortex are irrotational. MuraliMohan: Forced and Free Vortex are Rotational.		
	Who is/are correct? Justify your answer with examples.		
Q 4	<ul> <li>Imagine you are a pilot of a Boeing 757 Jet commercial aircraft. While flying this aircraft, when (and why) would you use:</li> <li>Leading edge slats</li> <li>Trailing edge flaps</li> </ul>	4	CO1
Q5	<ul> <li>a) Why is it that sometimes on narrow industrial Chimneys, spirals are made on the circumference? What specific purpose do they serve? Explain the underlying phenomenon.</li> <li>b) Citing the specific example of the recently launched Speedtail MaLaren sports car, enumerate what specific features can be had on a high speed car, to enable it to attain extremely high speeds? Present only the Fluid Mechanics perspectives.</li> </ul>	4	
	SECTION B		L
Q 6	Under certain conditions, wind blowing past a rectangular speed limit sign can cause the sign to oscillate with a frequency v. Assume that v is a function of the sign width, <i>b</i> , sign height, <i>h</i> , wind velocity, <i>V</i> , air density, r, and an elastic constant, <i>k</i> , for the supporting pole. The constant, <i>k</i> , has dimensions of <i>FL</i> . Develop a suitable set of pi terms for this problem.	10	CO2
Q 7	Determine the gage pressure in kPa at point a, if liquid A has SG = 1.20 and liquid B has SG = 0.75. The liquid surrounding point A is water, and the tank on the left is open to the atmosphere. $ \begin{array}{c}                                     $	10	CO2
Q 8	The pressure at section (2) shown in Fig. P8.73 is not to fall below 60 psi when the flowrate from the tank varies from 0 to 1.0 cfs and the branch line is shut off. Determine the minimum height, $h$ , of the water tank under the assumption that minor losses are not negligible.	10	CO4





Description of Flow Field	Velocity Potential	Stream Function	Velocity Componentsª
Uniform flow at angle $\alpha$ with the x axis (see Fig. 6.16b)	$\phi = U(x\cos\alpha + y\sin\alpha)$	$\psi = U(y \cos \alpha - x \sin \alpha)$	$u = U \cos \alpha$ $v = U \sin \alpha$
Source or sink (see Fig. 6.17) m > 0 source m < 0 sink	$\phi = \frac{m}{2\pi} \ln r$	$\psi = \frac{m}{2\pi} \theta$	$v_r = \frac{m}{2\pi r}$ $v_\theta = 0$
Free vortex (see Fig. 6.18) $\Gamma > 0$ counterclockwise motion $\Gamma < 0$ clockwise motion	$\phi = \frac{\Gamma}{2\pi}  \theta$	$\psi = -\frac{\Gamma}{2\pi} \ln r$	$v_r = 0$ $v_\theta = \frac{\Gamma}{2\pi r}$
Doublet (see Fig. 6.23)	$\phi = \frac{K\cos\theta}{r}$	$\psi = -\frac{K\sin\theta}{r}$	$v_r = -\frac{K\cos\theta}{r^2}$ $v_\theta = -\frac{K\sin\theta}{r^2}$

For the tornado shown above, determine :

- a) The expression for velocity potential.
- b) The expression for stream function.
- c) The radial and tangential velocities
- d) The radius beyond which the flow is incompressible.
- e) Find the gauge pressure at that radius



#### OR

The entrance region of a parallel, rectangular duct flow is shown in figure. The duct has a width W and height H, where W >> H. The fluid density  $\rho$  is constant, and the flow is steady. The velocity variation in the boundary layer of thickness  $\delta$  at station is assumed to be linear, and the pressure at any cross- section is uniform.

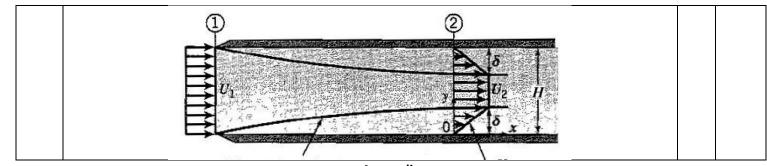
(a) Using the continuity equation, shows that  $U_1/U_2 = 1 - \delta/H$ .

(b) Find the pressure coefficient 
$$C_p = (p_1 - p_2)/(\frac{1}{2}\rho U_1^2)$$

(c) Show that

$$\frac{F_v}{\frac{1}{2}\rho U_1^2 W H} = 1 - \frac{U_2^2}{U_1^2} \left(1 - \frac{8\delta}{3H}\right)$$

Where  $F_{v}$  is the total viscous force acting on the walls of the duct?



<u>Appendix</u>

## Haaland Equation

$$\frac{1}{\sqrt{f}} = -1.8 \log \left[ \frac{6.9}{Re} + \left( \frac{\varepsilon/D}{3.7} \right)^{1.11} \right]$$

## **Conservation Equations in Cylindrical Coordinates:**

Continuity Equation:

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial (r \rho v_r)}{\partial r} + \frac{1}{r} \frac{\partial (\rho v_\theta)}{\partial \theta} + \frac{\partial (\rho v_z)}{\partial z} = 0$$

Momentum Equation:

(r direction)

$$\rho\left(\frac{\partial v_r}{\partial t} + v_r\frac{\partial v_r}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z\frac{\partial v_r}{\partial z}\right)$$
$$= -\frac{\partial p}{\partial r} + \rho g_r + \mu \left[\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial v_r}{\partial r}\right) - \frac{v_r}{r^2} + \frac{1}{r^2}\frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2}\frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2}\right]$$

( $\theta$  direction)

$$\begin{split} \rho \left( \frac{\partial v_{\theta}}{\partial t} + v_r \frac{\partial v_{\theta}}{\partial r} + \frac{v_{\theta}}{r} \frac{\partial v_{\theta}}{\partial \theta} + \frac{v_r v_{\theta}}{r} + v_z \frac{\partial v_{\theta}}{\partial z} \right) \\ &= -\frac{1}{r} \frac{\partial p}{\partial \theta} + \rho g_{\theta} + \mu \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_{\theta}}{\partial r} \right) - \frac{v_{\theta}}{r^2} + \frac{1}{r^2} \frac{\partial^2 v_{\theta}}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_{\theta}}{\partial z^2} \right] \end{split}$$

(z direction)

$$\rho\left(\frac{\partial v_z}{\partial t} + v_r\frac{\partial v_z}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_z}{\partial \theta} + v_z\frac{\partial v_z}{\partial z}\right) \\
= -\frac{\partial p}{\partial z} + \rho g_z + \mu \left[\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial v_z}{\partial r}\right) + \frac{1}{r^2}\frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2}\right]$$