	SE I - I	<b>KOII</b> NO:			
UNIVERSITY OF PETROLEUM AND ENERGY STUDIES End Semester Examination, Oct, 2017					
Program Name: M.Tech A&RE		Semester – I			
<b>Course Name : Electronics System</b>	ı Design	Max. Marks	: 100		
Course Code : ECEG7001		Duration	: 3 Hrs.		
No. of page/s: 2					

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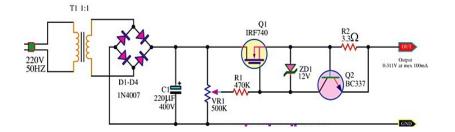
#### Section A: All Questions are compulsory

1 Discuss the voltage divider filter circuit used to calibrate the sensor [5] reading. Draw the circuit also for the same.

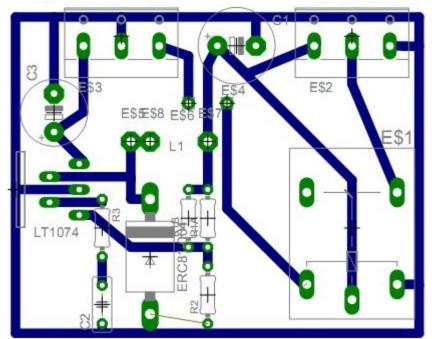
- 2 Discuss the MOSFET based power supply circuit used to drive a robot [5] wheels.
- 3 What is the role of a Zener diode and explain can it be possible to use [5] Zener diode for reducing back EMF from DC motor. Draw the circuit to support your answer if any.
- 4 Discuss the rules one should keep in mind while designing analog and [5] digital circuits.

#### Section B: Attempt All Questions.

- 5 Apply the fundamental rules of designing printed circuit board and [10] explain how the power supply section of PCB is designed and managed for 1.5 A of current.
- 6 Explain in detail the circuit shown below. The below circuit is [10] MOSFET based.



7 Below is the PCB design of a tiny robot. Comment on the circuit and [10] flaws of the design



8 Design and explain ULN2008 IC (motor driver) and explain the circuit [10] diagram and the digital logic for the rotation of stepper motor.

# Section C: Attempt All Questions

- 9 Design a digital IC which will be used to rotate the DC motor in a [20] clockwise direction to 12 clock cycles. The clock cycles can be assumed by the user. Design the IC using D flip-flop.
- 10 Design a sun tracking circuit for a Robot that will track the sun [20] positioning in real time

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## Section A: All Questions are compulsory

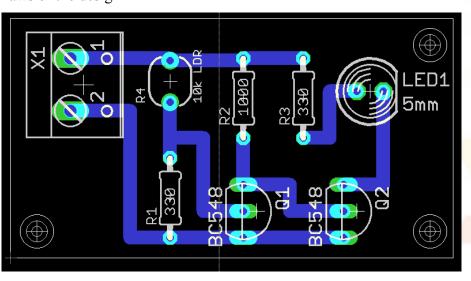
1 Discuss the various filter circuits used to calibrate the sensor reading. [5] Draw the circuit also for the same.

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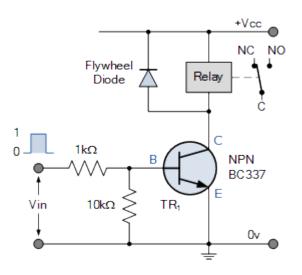
- 2 Discuss the transistor based H- bridge driver circuit used to drive a [5] robot wheels.
- 3 What is the role of a capacitor (ceramic and electrolytic) for reducing [5] back EMF from DC motor?
- 4 Discuss the rules one should keep in mind while designing digital ICs. [5]

## Section B: Attempt All Questions.

5 Below is the PCB design of a tiny robot. Comment on the circuit and [10] flaws of the design



Explain in detail the circuit shown below. The below circuit is relay based, can it be replaced with TRIAC. [10]



7 Apply the fundamental rules of designing printed circuit board and [10] explain how the power supply section of PCB is designed and managed

for 1.5 A of current.

8 Explain the MAX232 level converter IC and explain the circuit diagram [10] in detail. Also, explain the circuit for reading sensor values in terminal software.

# **Section C: Attempt All Questions**

- Design a triggering circuit for a robot movement in north and south direction that will trigger with a digital clock. When digital clocks count reaches to 8 the robot moves to north direction and else to the south direction. Design it using D flip-flop.
- 10 Design a sun tracking circuit for a Robot that will track the sun [20] positioning in real time.