Name:

**Enrolment No:** 



**Semester: VIII** Time 03 hrs.

Max. Marks: 100

## UNIVERSITY OF PETROLEUM AND ENERGY STUDIES **End Semester Examination, May 2019**

Course: Real Time Systems Program: B .Tech (CSE)-LLB-Cyber Law

**Course Code: CSEG 419** 

**Instructions:** 

	SECTION A Total marks= [5×4=20]		
S. No.	Attempt all question .Each question carry equal marks.	Marks	CO
Q 1	Define real time system .What are the characteristics of real time system. Explain with an example.	4	CO1
Q 2	What are the distinguishing characteristics of periodic, aperiodic, and sporadic real time tasks?	4	CO1
Q 3	Explain periodic task model? Explain period, execution time and phase periodic tasks.	4	CO5
Q 4	List out main differences between hard and soft real □ time communication supported by a network?	4	CO5
Q 5	What is real time communications? Why is real time communications important?	4	CO5
	SECTION B Total marks= [4×10=40]		
	Answer the following questions		
Q 6	Why are algorithms, which can satisfactorily schedule real □ time tasks on multiprocessors not satisfactory to schedule real □ time tasks on distributed systems?	10	CO4
Q 7	What is RAC? Discuss the effect of resource contention. Give advantages and disadvantages of priority inheritance protocol.	10	CO3
Q 8	State whether the following statements are TRUE or FALSE. Justify your answer. i) By extending EDF, we can generate optimal scheduling schemes for hard real  time tasks in multiprocessor computing environments. ii) RMA is optimal for scheduling access of several hard real □time periodic tasks to a certain shared critical resource.	10	CO4
Q 9	Explain Rate Monotonic Scheduling Algorithms? What are various assumption in this algorithm? Explain Rate Monotonic Scheduling with example.  OR  What is aperiodic task scheduling? Explain assumption and approaches for aperiodic	10	CO2

	task schedul	_	ION C. T. 4.1	1 [202	401		
		SECT	ION-C Total 1	narks=  20×2=	·40]		
	Answer the	following questions					
Q 10	Explain the rules of basic priority ceiling protocol .consider the following system of five jobs, schedule the following five jobs with basic priority ceiling protocol						
	Job	ri	e <sub>i</sub>	$\pi_{i}$	Critical section		
	J1	7	3	1	[Shaded;1]	20	CO <sub>3</sub>
	J2	5	3	2	[Black;1]	_0	
	J3	4	2	3	, J		
	J4	2	6	4	[Shaded;4[Bla ck;1.5]		
	J5	0	6	5	[Black;4]		
	Consider sc (EDF),the R repetition pe defined in t timing Diagr	, , , , ,					CO2
	Task	Release Time	Execution Time	Period	Deadline		
	T1	0	0.5	2	2		
	T2	1	2	6	6		
	T3	3	1.8	10	10		

Name:	<b>UPES</b>					
Enrolment No:	UNIVERSITY WITH A PURPOSE					

## UNIVERSITY OF PETROLEUM AND ENERGY STUDIES

End Semester Examination, May 2019 Course: Real Time Systems

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Course: Real Time Systems

Program: B .Tech (CSE)-LLB-Cyber Law

Semester: VIII
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Course Code: CSEG 419 Max. Marks: 100

## **Instructions:**

## SECTION A Total marks= [5×4=20]

Marks

 $\mathbf{CO}$ 

recompt an question search question carry equal marks.	Mains	
What is a real time system? Explain its various components with a suitable block diagram.	4	CO1
What is the difference between a performance constraint and a behavioral constraint in a real \(\subseteq\) time system?	4	CO1
Explain the important differences between hard, firm and soft real time systems.	4	CO1
List out main differences between offline and online scheduling with examples.	4	CO2
Differentiate between synchronous and asynchronous I/O? Which one is better suited for use in real time applications?	4	CO5
SECTION B		
Total marks= [4×10=40]		
Answer the following questions		
Explain offline and online scheduling and list out main differences between offline and online scheduling with examples.	10	CO2
What is resource access control? Discuss the effect of resource contention. Give advantages and disadvantages of priority inheritance protocol.	10	CO3
Explain basic priority ceiling protocol and priority inheritance protocol in detail?	10	CO3
State whether the following statements are TRUE or FALSE. Justify your answer.  i) By extending EDF, we can generate optimal scheduling schemes for hard real □ time tasks in multiprocessor computing environments.  ii) RMA is optimal for scheduling access of several hard real □ time periodic tasks to a certain shared critical resource.  OR  Why are algorithms, which can satisfactorily schedule real □ time tasks on multiprocessors not satisfactory to schedule real □ time tasks on distributed systems?	10	CO4
	What is a real time system? Explain its various components with a suitable block diagram.  What is the difference between a performance constraint and a behavioral constraint in a real □time system?  Explain the important differences between hard, firm and soft real time systems.  List out main differences between offline and online scheduling with examples.  Differentiate between synchronous and asynchronous I/O? Which one is better suited for use in real □time applications?  SECTION B  Total marks= [4×10=40]  Answer the following questions  Explain offline and online scheduling and list out main differences between offline and online scheduling with examples.  What is resource access control? Discuss the effect of resource contention. Give advantages and disadvantages of priority inheritance protocol.  Explain basic priority ceiling protocol and priority inheritance protocol in detail?  State whether the following statements are TRUE or FALSE. Justify your answer. i) By extending EDF, we can generate optimal scheduling schemes for hard real □ time tasks in multiprocessor computing environments.  ii) RMA is optimal for scheduling access of several hard real □ time periodic tasks to a certain shared critical resource.  OR  Why are algorithms, which can satisfactorily schedule real □ time tasks on	What is a real time system? Explain its various components with a suitable block diagram.  What is the difference between a performance constraint and a behavioral constraint in a real □ time system?  Explain the important differences between hard, firm and soft real time systems.  List out main differences between offline and online scheduling with examples.  Differentiate between synchronous and asynchronous I/O? Which one is better suited for use in real □ time applications?  SECTION B  Total marks= [4×10=40]  Answer the following questions  Explain offline and online scheduling and list out main differences between offline and online scheduling with examples.  What is resource access control? Discuss the effect of resource contention. Give advantages and disadvantages of priority inheritance protocol.  Explain basic priority ceiling protocol and priority inheritance protocol in detail?  State whether the following statements are TRUE or FALSE. Justify your answer.  i) By extending EDF, we can generate optimal scheduling schemes for hard real □ time tasks in multiprocessor computing environments.  ii) RMA is optimal for scheduling access of several hard real □ time periodic tasks to a certain shared critical resource.  OR  Why are algorithms, which can satisfactorily schedule real □ time tasks on

			SECTIO Total marks=			•	
	Answer the	e following question		. ,			
Q 10	Write short notes on the following  i) Critical section ,Mutual execution  ii) Fixed priority vs Dynamic priority scheduling  iii) Firm deadline model  iv) Real time work load Vs Real time Scheduling				20	CO4	
Q 11	Determine whether the following set of periodic real □ time tasks is schedulable on a uniprocessor using RMA.         Task       Start time       Processing       Period (ms)       Deadline (ms)						
	T1	(ms) 20	time (ms)	150	100		
	T2	40	7	40	40		
	T3	60	10	60	50		
	T4	25	10	30	20		
	OR What is aperiodic task scheduling ?explain assumption an approaches for aperiodic task scheduling .A system have task such as					20	CO5
			xecution time	Perio	d		
	T1		2 10				
	T2		5 15				
	T3	9	9 25				