

Name:

Enrolment No:



UPES

End Semester Examination, May 2025

Program Name : M Tech Chemical Engineering

Course Name : Advanced Process Control

Course Code : CHPD 7013

Nos. of page(s) : 02

Semester : II

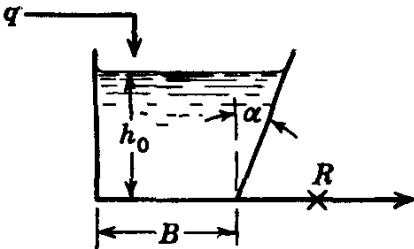
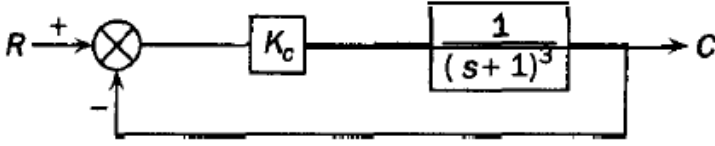
Time : 3 hours

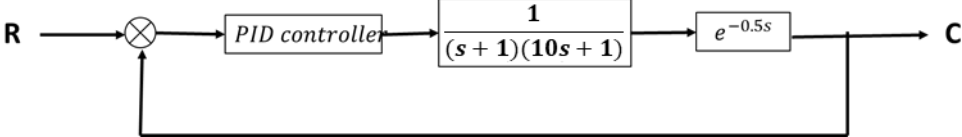
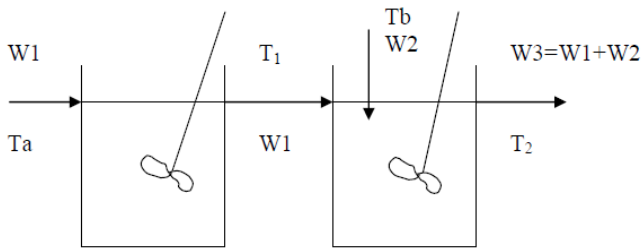
Max. Marks: 100

**SECTION A**  
(5QX4M=20 marks)

S. No.		Marks	CO
1	<b>Outline</b> in detail LVDT with a neat diagram. State various applications of LVDT in the industry.	4	CO1
2	<b>Recall</b> about the inherent characteristics of control valves	4	CO1
3	<b>Describe</b> bode stability criteria and crossover frequency	4	CO2
4	<b>Explain</b> what is root locus	4	CO2
5	<b>Interpret</b> the substitution rule.	4	CO3

**SECTION B**  
(4QX4M=40 marks)

6	A thermometer having first-order dynamics with a time constant of 1 min is placed in a temperature bath at 100°F. After the thermometer reaches steady state, it is suddenly placed in a bath at 110°F at $t = 0$ and left there for 1 min, after which it is immediately returned to the bath at 100°F. <b>Identify</b> the thermometer reading at $t = 0.5$ min and at $t = 2.0$ min.	10	CO2
7	<p><b>Demonstrate</b> a formula for finding the time constant of the liquid-level system shown below, when the average operating level is <math>h_0</math>. The resistance <math>R</math> is linear. The tank has three vertical walls and one which slopes at an angle <math>\alpha</math> from the vertical as shown in figure. The distance separating the parallel walls is 1.</p> 	10	CO3
8	 <p>In the control system shown above, <b>calculate</b> the value of <math>K_c</math> for which the system is on the verge of the instability. The controller is replaced by a PD controller, for which</p>	10	CO4

	the transfer function is $K_c(1+\tau_{DS})$ . if $K_c = 10$ , determine the range of $\tau_D$ for which the system is stable.		
9	<p>Using Ziegler-Nichols rules, <b>design</b> proportional gain, derivative and integral time for the system shown below. (Do not plot the bode diagram and use Bode stability criterion)</p>  <p style="text-align: center;"><b>OR</b></p> <p>With a neat diagram explain the distillation column control system by explaining the types of controllers that could be used.</p>	10	CO5
<b>SECTION C</b> <b>(2Q X 20M=40 marks)</b>			
10	<p>The two tank heating process shown in figure below consist of two identical , well stirred tanks in series. At steady state <math>T_a = T_b = 60^\circ\text{F}</math>. At <math>t = 0</math> , temp of each stream changes according to a step function <math>T_a'(t) = 10 u(t)</math> <math>T_b'(t) = 20 u(t)</math></p> <p>(a) <b>Choose</b> a block diagram that relates <math>T_2'</math> , the deviation in the temp of tank2, to <math>T_a'</math> and <math>T_b'</math>.</p> <p>(b) <b>Illustrate</b> an expression for <math>T_2'(s)</math> and <math>T_2'(t)</math></p> <p><math>W_1 = W_2 = 250 \text{ lb/min}</math>  <math>V_1 = V_2 = 10 \text{ ft}^3</math>  <math>\rho_1 = \rho_2 = 50 \text{ lb/ft}^3</math>  <math>C = 1 \text{ Btu/lb } (^\circ\text{F})</math></p>  <p style="text-align: center;"><b>OR</b></p> <p>Plot the root locus <b>diagram</b> for the open loop transfer function</p> $\frac{K(s+6)}{s(s+2)(s+4)(s+9)}$	20	CO3
11	<p>With neat diagrams and appropriate process and block diagrams <b>appraise</b> any two of the following</p> <ol style="list-style-type: none"> <li>1. Smith Predictor</li> <li>2. Ratio controller</li> <li>3. Cascade controller</li> </ol>	20	CO5